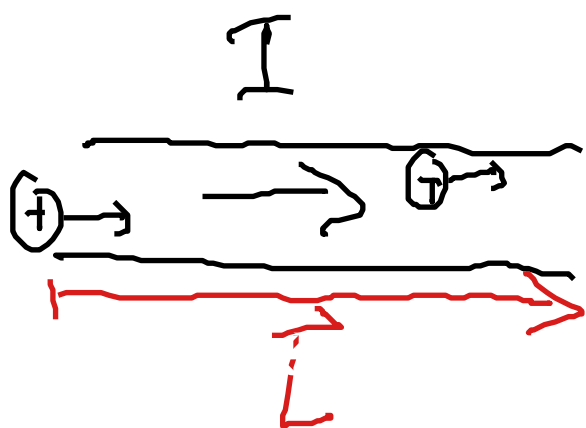


$$\vec{F} = q \vec{v} \times \vec{B}$$



$|\vec{L}| = \text{length of wire}$

$$\vec{F} = I \vec{L} \times \vec{B}$$

$$|\vec{F}| = I L B \sin \phi$$

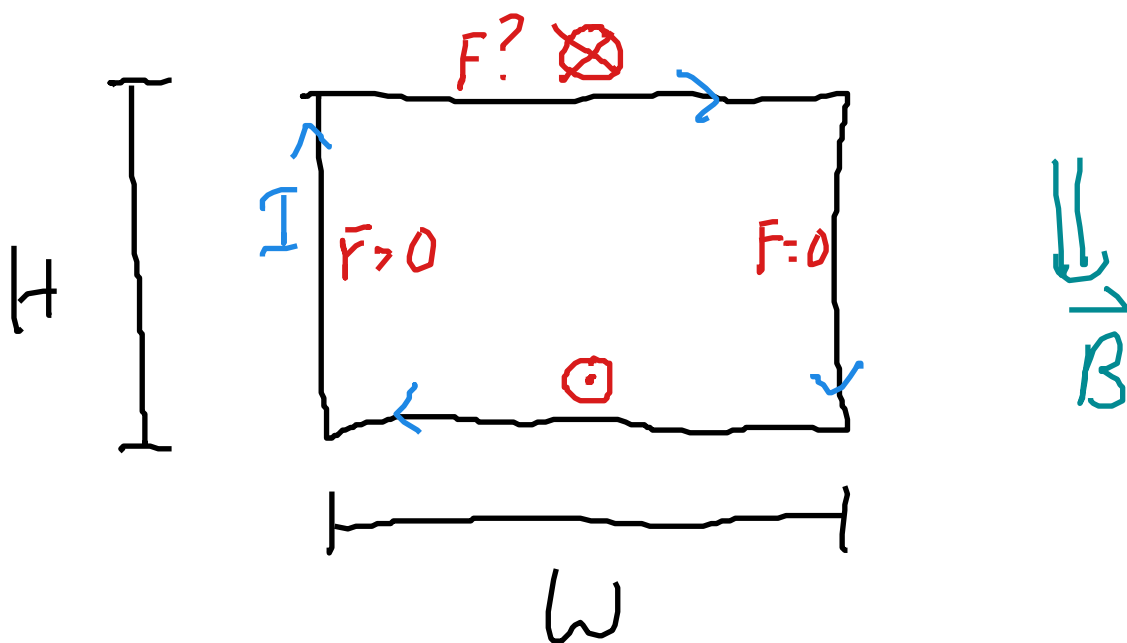


could also
write

$$\vec{F} = L \vec{I} \times \vec{B}$$

but won't

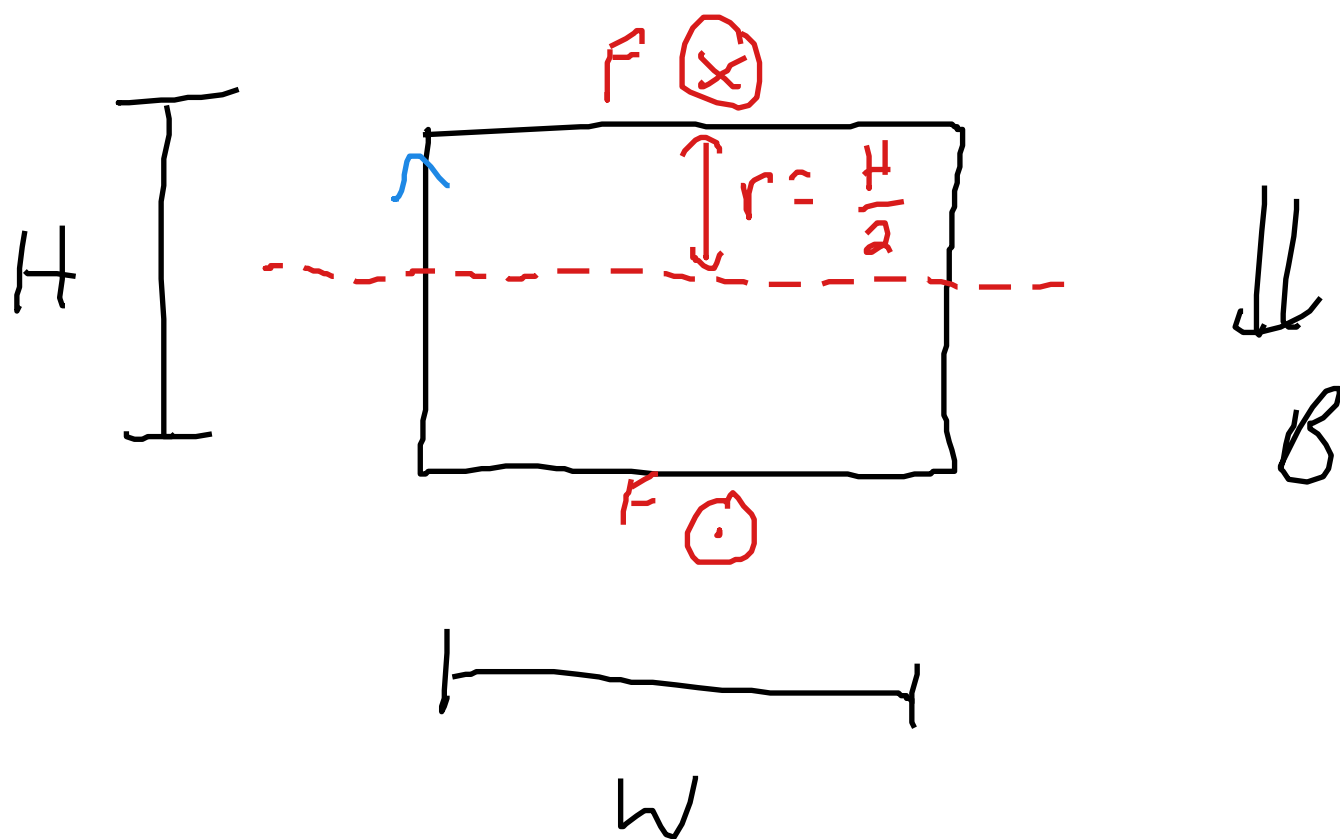
Loop of Wire



$$\vec{F}_{\text{net}} = \overset{\text{top}}{I W B \otimes} + \overset{\text{bottom}}{I W B \odot}$$

$$= \bigcirc$$

but it will feel a torque

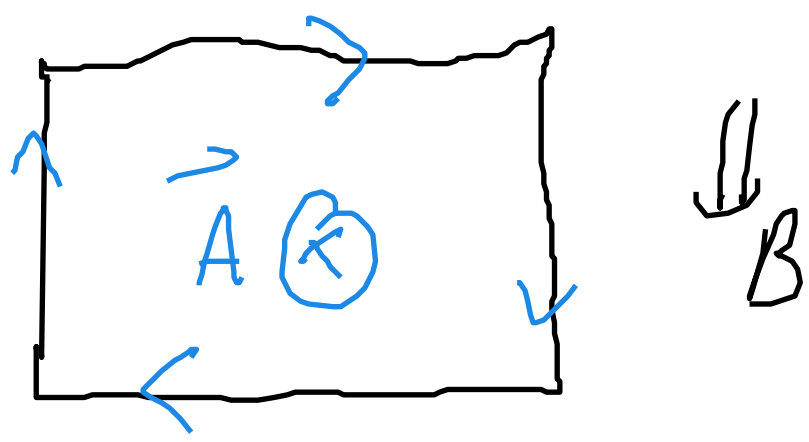


$$\tau = r_{\perp} F$$

$$\tau = \frac{H}{2} I W B \rho + \frac{H}{2} I W B \rho$$

$$\tau = I \underline{H W} B \rho$$

$$= I A B \rho$$



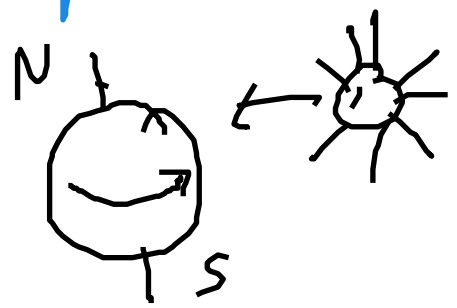
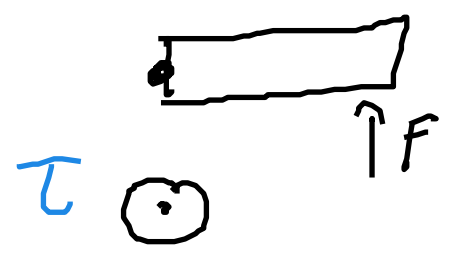
Define $\vec{A}$ using a
"circle - line RHR"

fingers curl around current
thumb points in direction of $\vec{A}$

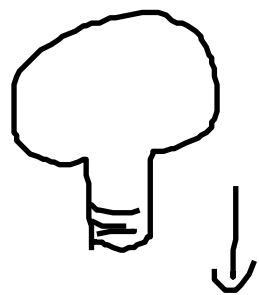
$$\vec{\tau} = I \vec{A} \times \vec{B}$$

thumb: points in direction of $\vec{\tau}$

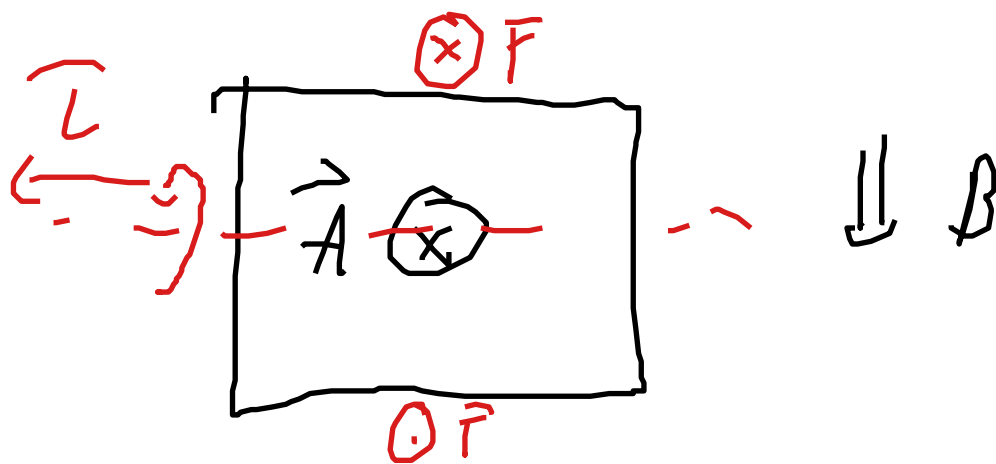
fingers show tendency to spin
 τ points along axis



$\vec{\omega} = \uparrow$ North

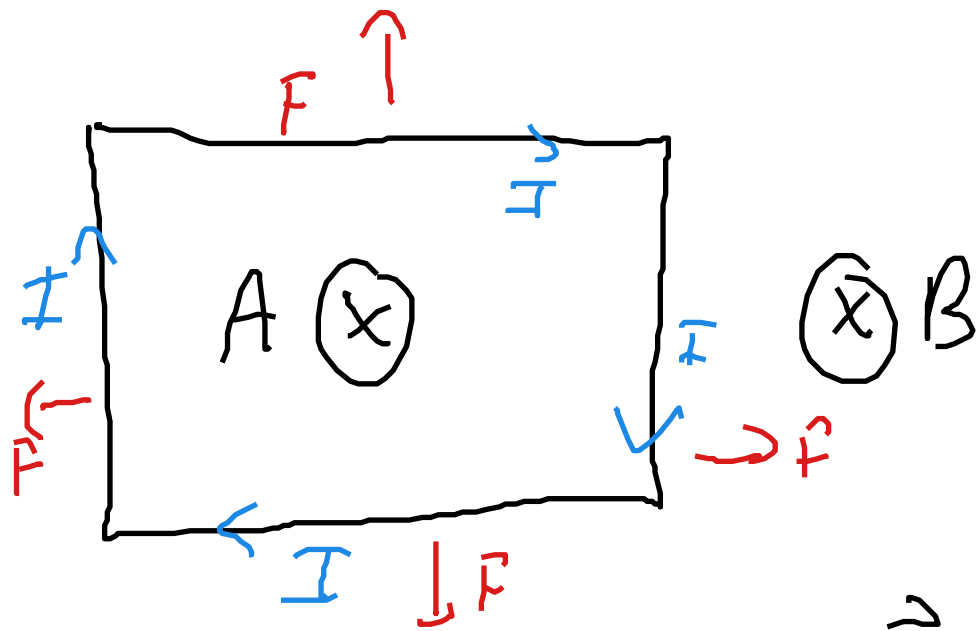


Screw light bulb in
apply $\downarrow \vec{\tau}$



$$\tau = I \vec{A} \times \vec{B} = IAB \leftarrow$$

after it
spins &
while
(top view)



$$\tau = I \vec{A} \times \vec{B} = 0$$

Point of stable equilibrium

$$\vec{F}_{\text{net}} = 0$$

$$\vec{\tau}_{\text{net}} = 0$$

put loop in another configuration -
it will tend to end up in

this one

$$\vec{A} \otimes \otimes \vec{B}$$

stable eq. when

$\vec{A}$ & $\vec{B}$ point

just like a compass needle in the same direction